When is the Normalized Edit Distance over Non-Uniform Weights a Metric?

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The Edit (Levenshtein) Distance

Types of operations:

- Delete the letter σ
- Insert the letter σ ٠
- Substitute the letter σ with σ' ٠

No change ٠

Uniform weight aabede w1 aab_ede we= abpcg _abpcg_ The edit $\begin{bmatrix} a \\ \epsilon \end{bmatrix} \begin{bmatrix} a \\ a \end{bmatrix} \begin{bmatrix} b \\ b \end{bmatrix} \begin{bmatrix} \varepsilon \\ p \end{bmatrix} \begin{bmatrix} c \\ c \end{bmatrix} \begin{bmatrix} d \\ g \end{bmatrix} \begin{bmatrix} e \\ \epsilon \end{bmatrix}$ The edit path cost: 4

 $ED(w_1, w_2) = min \{ weight of ops needed to transforms w_1 \}$ to w_2 {

ع ا

 $\begin{bmatrix} \varepsilon \\ \sigma \end{bmatrix}$

 $\lfloor_{\sigma} \rfloor$

1

1

1

0

Issue with ED





But these are much more similar

How can we normalize ED?

• The sum edit-distance: $ED_{sum}(w_1, w_2)$

$$= \frac{ED(w_1, w_2)}{|w_1| + |w_2|}$$

• The max edit-distance: $ED_{max}(w_1, w_2)$

 $=\frac{ED(w_1, w_2)}{max(|w_1|, |w_2|)}$

© Ilay Tzarfati All the above <u>do not</u> satisfy the triangle inequality! (hence is not a metric)

How can this be solved? Marzal and Vidal suggested dividing by the length of the edit path

[Marzal & Vidal 93] Normalizing using path length



 w_2) = min { cost(P): P is an edit path transforming w_1 to w_2 } © Ilay Tzarfati



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[Marzal & Vidal 93] NED- Normalized Edit Distance

 w_1, w_2 = min { cost(P): P is an edit path transforming w_1 to w_2 }





Cost(P) =

Matches our intuition \bigcirc

But is it a metric ???

Is NED a Metric ?

Normalized Edit Distance (NED) Generalized Edit Distance (GED)

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Computation of Normalized Edit Distance and Applications

Andrés Marzal and Enrique Vidal

Abstract—Given two strings X and Y over a finite alphabet, the normalized edit distance between X and Y, d(X, Y) is defined as the minimum of W(P)/L(P), where P is an editing path between X and Y, W(P) is the sum of the weights of the elementary edit operations of P, and L(P) is the number of these operations (length of P). In this paper, it is shown that algorithm is shown to work in $O(m \cdot n^2)$ time and $O(n^2)$ in general, d(X,Y) cannot be computed by first obtaining the conventional (unormalized) edit distance between X and Y and then normalizing this value by the length of the corresponding editing path. In order to compute normalized edit distances, a new algorithm that can be implemented to work in $O(m \cdot n^2)$ time and $O(n^2)$ memory space is proposed, where m and n are the lengths of the strings under consideration, and $m \ge n$. Experiments in hand-written digit recognition are presented, revealing that the normalized edit distance consistently provides better results than both unnormalized or post-normalized classical edit distances.

properly defined normalized edit distances cannot, in general, be carried out by using the algorithms that are known thus far for computing edit distances. In order to compute these normalized edit distances, a new algorithm is introduced. This memory space for strings of lengths m and n, and $n \leq m$.

II. REVIEW OF EDIT DISTANCES

Let Σ be a finite alphabet and Σ^* be the set of all finitelength strings over Σ . Following a notation similar to that used in the classical paper of Wagner and Fisher [13], let $X = X_1 X_2 \dots X_n$ be a string of Σ^* , where X_i is the *i*th cumbal of Y We denote by Y. . the substring of Y that

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A Normalized Levenshtein Distance Metric

Li Yujian and Liu Bo

Abstract-Although a number of normalized edit distances presented so far may offer good performance in some applications, none of them can be regarded as a genuine metric between strings because they do not satisfy the triangle inequality. Given two strings X and Y over a finite alphabet, this paper defines a new normalized edit distance between X and Y as a simple function of their lengths (|X| and |Y|) and the Generalized Levenshtein Distance (GLD) between them. The new distance can be easily computed through GLD with a complexity of $O(|X| \cdot |Y|)$ and In terms of notation, Σ is the alphabet and Σ' is the set of strings over it is a metric valued in [0, 1] under the condition that the weight function is a metric over the set of elementary edit operations with all costs of insertions/deletions having the same weight. Experiments using the AESA algorithm in handwritten digit recognition show that the new distance can generally provide similar results to some other normalized edit distances and may perform slightly better if the triangle inequality is violated in a particular data set.

Index Terms-Sequence comparison, Levenshtein distance, normalized edit distance, metric, AESA.

hand, normalized metrics for symmetric set difference and Euclidian distance do not apply to edit distance [13] nor do those metrics based on Lempel-Ziv complexity [14]. Until now, defining a normalized edit distance that can be regarded as a genuine metric between two strings has remained an unsolved problem. This communication presents a solution for defining such a metric

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[Yujian & Bo '07]

as a simple function of the string lengths and the GLD.

 Σ . $\lambda \notin \Sigma$ is the null string. A string $X \in \Sigma^{\circ}$ is denoted as $X = x_1 x_2 \dots x_n$, where x_i is the *i*th symbol of X. X_i , is referred to as the substring of X including the symbols from x_i to x_i , $1 \le i \le j \le n$, its length is defined as $|X_{i\dots j}| = j - i + 1$, and it is the null string $\lambda(|\lambda| = 0)$ if i > j. An elementary edit operation is a pair $(a, b) \neq (\lambda, \lambda)$, often written as $a \rightarrow b$, where both a and b are strings of lengths 0 or 1. The forms $\lambda \rightarrow a$, $a \rightarrow b$, and $b \rightarrow \lambda$, respectively, represent insertions, substitutions, and deletions that are the three types of elementary edit operations, $T_{YY} = T_1 T_2 \dots T_n$ is used to denote an edit transformation of X into Y that is a

Contextual Edit Distance (CED)

A Contextual Normalised Edit Distance

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Abstract

In order to better fit a variety of pattern recognition problems over strings, using a normalised version of the edit or Levenshtein distance is considered to be an appropriate approach. The goal of normalisation is to take into account the lengths of the strings. We define a new normalisation, contextual, where each edit operation is divided by the length of the string on which the edit operation takes place. We prove that this contextual edit distance is a metric and that it can be comcally by the length of the string on which it is applied. We argue that this contextual edit distance reaches the following compromise:

- It is a metric, and respects the triangle inequality. It can therefore be used for algorithms that rely on this inequality in order not to explore the entire space
- · It corresponds to the nature of normalisations proposed by different authors, as it is closely related with the lengths of the strings [4]

[de la Higuera & Mico'08]

[Marzal & Vidal 93]

The Problem



If d is uniform, it is !

The Normalized Edit Distance with Uniform

Operation Costs is a Metric

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— Abstract —

We prove that the normalized edit distance proposed in [Marzal and Vidal 1993] is a metric when the cost of all the edit operations are the same. This closes a long standing gap in the literature where several authors noted that this distance does not satisfy the triangle inequality in the general case, and that it was not known whether it is satisfied in the uniform case — where all the edit costs are equal. We compare this metric to two normalized metrics proposed as alternatives in the literature, when people thought that Marzal's and Vidal's distance is not a metric, and identify key properties that explain why the original distance, now known to also be a metric, is better for some applications. Our examination is from a point of view of formal verification, but the properties and their significance are stated in an application agnostic way.

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Our main result

A necessary and sufficient condition for NED_d to be a Metric.

Surprisingly, d being a metric is neither sufficient nor necessary.

Essential edit operations

An edit operation is **essential**, if there exist optimal edit path that use it.



 $\forall a \in \Sigma$, (a,ε) and (ε,a) are essential.

 $d(a,b) \ge d(a,\varepsilon) + d(\varepsilon,b)$ iff (a,b) is inessential.

$d(a,\varepsilon) = d(\varepsilon,a) = 0.4 \text{ w1=a}$ w2=b
$d(b,\varepsilon) = d(\varepsilon,b) = 0.3$ $d(a,b) = d(b,a) = 0.8 \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \begin{bmatrix} \varepsilon \\ b \end{bmatrix}$
NED_d (w1,w2) = $\frac{0.4+0.3}{2}$ = 0.35

In the example both (a,b), (b,a) are inessential

The Necessary and sufficient condition for NED, to be a Metric Weight function : Let $d: (\Sigma \cup \{\varepsilon\}) \times (\Sigma \cup \{\varepsilon\})$ $\rightarrow [0,1]$ $a,c \in \Sigma \cup \{\varepsilon\}$ and b \checkmark 1. identity: $\in \Sigma$ d(a,c)' = 0 iff a=c \checkmark 2. symmetry: d(a,c) = d(c,a)? 3. Relaxed triangle inequality: $d(a,b) + d(b,c) \ge \min \{ d(a,c), d(a,c) +$? \$ (EAE) least half: A d satisfying those properties, is termed $d(\varepsilon,b) = d(b,\varepsilon) \geq \frac{1}{2}$

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Obviously to satisfy the triangle inequality we need:
$$d(a,c) \leq d(a,b) + d(b,c)$$



But since we know that d(a,c) can be replace with $d(a,\varepsilon)$, $d(\varepsilon,c)$ we require that:

 $\min\{d(a,c), d(a,\varepsilon) + d(\varepsilon,c)\} \leq d(a,b) + d(b,c)$

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Sketch of the idea: At least half

We want to make sure that inflating the edit path is not worthwhile.

$$d(b,\varepsilon) = d(\varepsilon, b) \geq \frac{1}{2}$$

$w_1 = a w_2 = ac^{100} w_3 =$	edit path $[w_1 \rightarrow w_2]$:
b	$\begin{bmatrix} a \\ a \end{bmatrix} \begin{bmatrix} \varepsilon \\ c \end{bmatrix} \dots \begin{bmatrix} \varepsilon \\ c \end{bmatrix} \begin{bmatrix} \varepsilon \\ c \end{bmatrix}$
d(a,b) = d(b,a) = 0.55, d(a,c) = d(c,a) = d(b,c) = d(c,b) = 0.5.	cost $\frac{100*0.2}{101} = 0.198$ edit path $[w_2 \rightarrow w_3]$; EDd 4
Optimal edit path $[w_1 \rightarrow w_3]$: $\begin{bmatrix} a \\ b \end{bmatrix}$ cost : 0.55.	$\begin{bmatrix} a \\ b \end{bmatrix} \begin{bmatrix} c \\ \varepsilon \end{bmatrix} \cdots \begin{bmatrix} c \\ \varepsilon \end{bmatrix} \begin{bmatrix} c \\ \varepsilon \end{bmatrix} \begin{bmatrix} c \\ \varepsilon \end{bmatrix} \begin{bmatrix} b \\ \varepsilon \end{bmatrix} \cdots \begin{bmatrix} c \\ \varepsilon \end{bmatrix} \begin{bmatrix} c \\ \varepsilon \end{bmatrix}$
	$cost \frac{100*0.2+0.5}{101} = 0.203$

- 1. identity: d(a,c) = 0 iff a=c
- 2. symmetry: d(a,c) = d(c,a)

3. Relaxed triangle inequality :

$$d(a,b) + d(b,c) \ge \min \{ d(a,c), d(a,c) + d(c,c) \}$$

4. At least half:
 $d(c,b) = d(b,c) \ge \frac{1}{2}$

sufficient condition

d is fine $\rightarrow NED_d$ is metric

Let $w_1, w_2, w_3 \in \Sigma^*$:

- 1. NED_d (w_1, w_2) = 0 iff $w_1 = w_2$
- 2. NED_d (w_1, w_2) = NED_d (w_2, w_1)
- **3.** NED_d (w_1, w_2) + NED_d (w_2, w_3) $\geq NED_d$ (w_1, w_3)



Proof idea:

 $w_2 = bb$ w1 =w3 = $P(1-2) = \begin{bmatrix} \varepsilon \\ \varepsilon \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} \begin{bmatrix} \varepsilon \\ \varepsilon \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} \begin{bmatrix} \varepsilon \\ \varepsilon \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} \begin{bmatrix} \varepsilon \\ \varepsilon \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} \begin{bmatrix} \varepsilon \\ \varepsilon \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} \begin{bmatrix} \varepsilon \\ \varepsilon \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \end{bmatrix} \begin{bmatrix} a \\ \varepsilon \end{bmatrix} \end{bmatrix} \begin{bmatrix} a$ aaa CCCC $P(1->2) = \begin{bmatrix} a \\ b \end{bmatrix} \begin{bmatrix} a$ P (2->3) = _b_b $\begin{bmatrix} \varepsilon \\ c \end{bmatrix} \begin{bmatrix} b \\ c \end{bmatrix} \begin{bmatrix} \varepsilon \\ \varepsilon \end{bmatrix} \begin{bmatrix} c \\ c \end{bmatrix} \begin{bmatrix} \varepsilon \\ c \end{bmatrix} \begin{bmatrix} \varepsilon \\ c \end{bmatrix} =$ eccc $= \begin{bmatrix} \varepsilon \\ c \end{bmatrix} \begin{bmatrix} b \\ c \end{bmatrix} \begin{bmatrix} b \\ c \end{bmatrix} \begin{bmatrix} \varepsilon \\ c \end{bmatrix}$ C cccc Problem [^e][^a][^a][^a][^e] ^c]^e]^c]^c _c]^u

Examples for fine d's

Distances in [0,n]: Let $d: [0,n] \times [0,n] \rightarrow [0,1]$ be defined as follows :

$$d(n_1, n_2) = \frac{|n_1 - n_2|}{n+1}$$

Distances in \mathbb{N} : Let $d: \mathbb{N} \times \mathbb{N} \to [0,1]$ be defined as follows :

$$d(n_1, n_2) = 1 - \frac{1}{|n_1 - n_2| + 1}$$

Distances in $\Sigma = 2^k$: Let $d: 2^k \times 2^k \rightarrow [0,1]$ be defined as follows :

$$d(v_1, v_2) = \frac{HD(v_1, v_2)}{k}$$

NEDa is metric

Applications in Formal Verification

- FV requires ω -words
 - Robustness requires NED between omega-words
- [FGW23] suggested ωNED
- ωNED can be generalized to ωNED_d
- Same algorithms are applicable.

•

Paper results

- We have shown necessary and sufficient conditions for NED_d to be metric.
- We have shown several fine d's.
- We have shown that NED_d can also be used for formal verification.

Thanks for Listening ! Any questions?